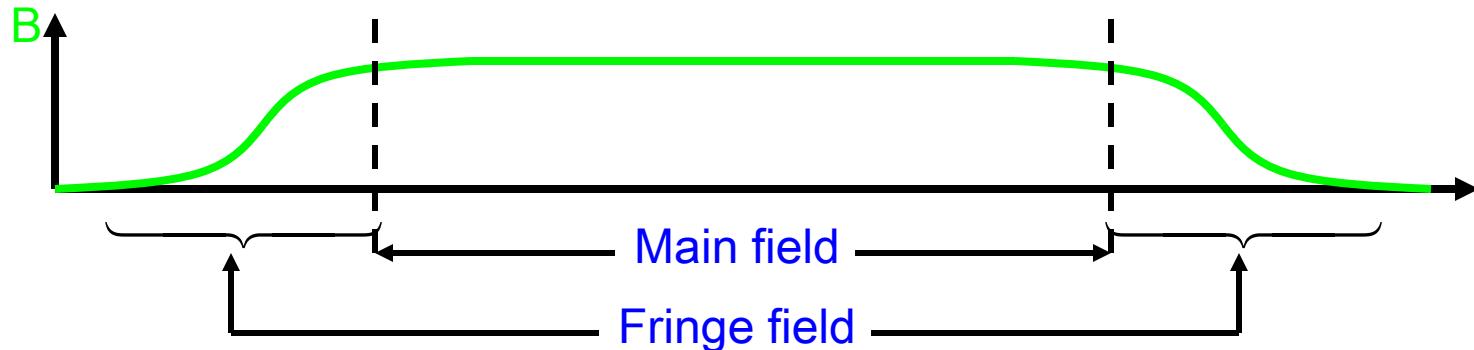




Fringe Fields and Main Fields



CHESS & LEPP



Only the fringe field region has terms with $\lambda \neq 0$ and $\partial_z^2\psi \neq 0$

Main fields in accelerator physics: $\lambda = 0$, $\partial_z^2\psi = 0$

$$\Psi_\nu = \begin{cases} e^{i\nu\vartheta_\nu} |\Psi_\nu| & \text{for } \nu \neq 0 \\ i |\Psi_0| & \text{for } \nu = 0 \end{cases}$$

$$\psi(r, \varphi) = \sum_{\nu=1}^{\infty} r^\nu |\Psi_\nu| \operatorname{Im}\{e^{-i\nu(\varphi - \vartheta_\nu)}\} + |\Psi_0|$$



Main Field Potential



CHESS & LEPP

Main field potential:

$$\psi = |\Psi_0| - \sum_{\nu=1}^{\infty} r^{\nu} |\Psi_{\nu}| \sin[\nu(\varphi - \vartheta_{\nu})]$$

The isolated multipole:

$$\psi = -r^{\nu} |\Psi_{\nu}| \sin(\nu\varphi)$$

Where the rotation ϑ_{ν} of the coordinate system is set to 0

The potentials produced by different multipole components Ψ_{ν} have

- a) Different rotation symmetry C_{ν}
- b) Different radial dependence r^{ν}

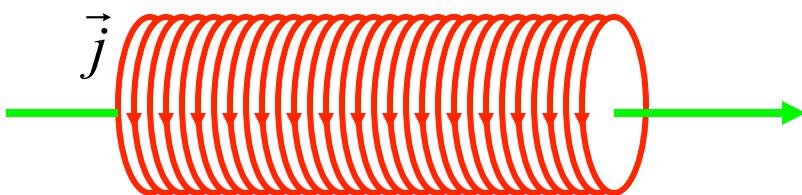


Multipoles in Accelerators

$v=0$: Solenoids



CHESS & LEPP



$$m\gamma \begin{pmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{z} \end{pmatrix} = q \begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{z} \end{pmatrix} \times \begin{pmatrix} -\frac{x}{2} B_z' \\ -\frac{y}{2} B_z' \\ B_z \end{pmatrix}$$



$$\begin{pmatrix} \ddot{x} \\ \ddot{y} \end{pmatrix} = \frac{qB_z}{m\gamma} \begin{pmatrix} \dot{y} \\ -\dot{x} \end{pmatrix} + \frac{qB_z'}{2m\gamma} \dot{z} \begin{pmatrix} y \\ -x \end{pmatrix}$$



$$\ddot{w} = -i \frac{qB_z}{m\gamma} \dot{w} - i \frac{qB_z'}{2m\gamma} w$$

$$\psi = \Psi_0(z) - \frac{w\bar{w}}{4} \Psi_0''(z) \pm \dots$$

$$\vec{B} = \begin{pmatrix} \frac{x}{2} \Psi_0'' \\ \frac{y}{2} \Psi_0'' \\ -\Psi_0' \end{pmatrix} \Rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$g = \frac{qB_z}{2m\gamma}, \quad w_0 = w e^{i \int_0^t g dt}$$

$$\begin{aligned} \ddot{w}_0 &= (\ddot{w} + i2g\dot{w} + i\dot{g}w - g^2w)e^{i \int_0^t g dt} \\ &= -g^2w_0 \end{aligned}$$

$$\ddot{x}_0 = -g^2x_0$$

$$\ddot{y}_0 = -g^2y_0$$

Focusing in a rotating coordinate system.

For const. g : $x_0(t) = \cos[g(t - t_0)]x_0(0)$