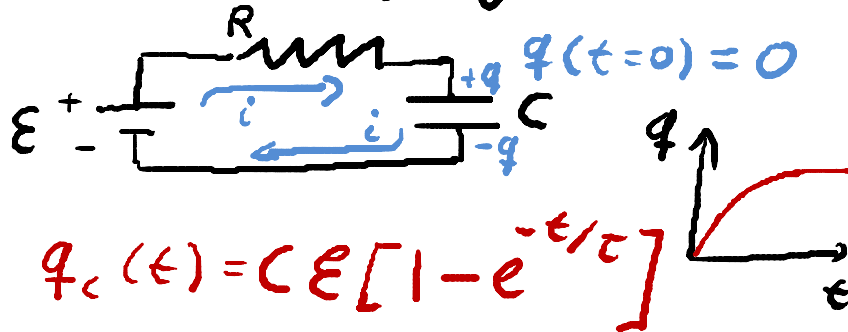


# Recap

## Lecture 14

### • RC circuit:

Charging:

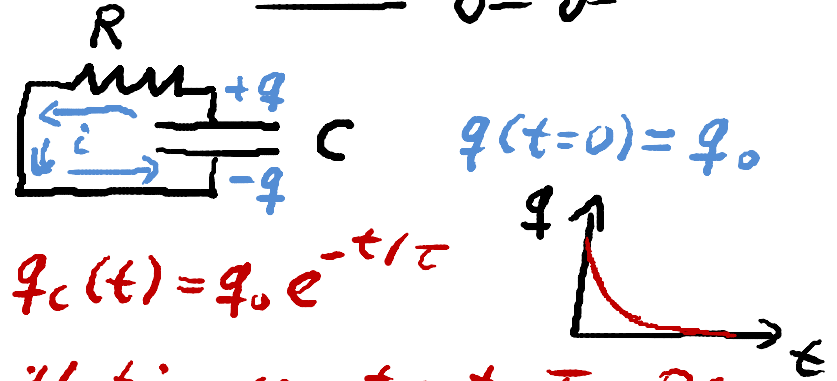


$$q_c(t) = C\epsilon [1 - e^{-t/\tau}]$$

with time constant  $\tau = RC$

$$\Rightarrow i(t) = \frac{dq}{dt} = \frac{\epsilon}{R} e^{-t/\tau}$$

Discharging:



$$q_c(t) = q_0 e^{-t/\tau}$$

with time constant  $\tau = RC$

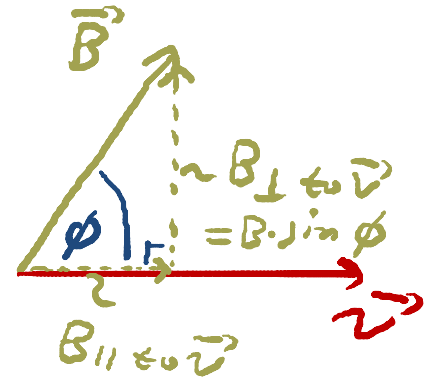
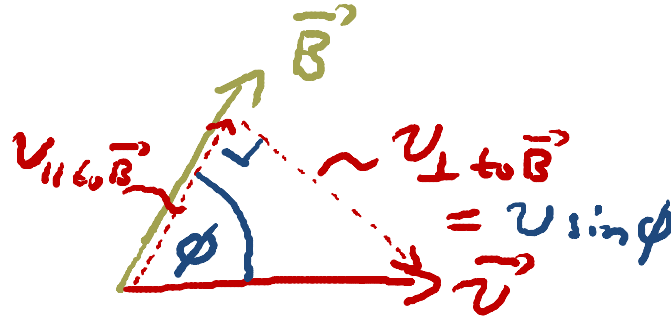
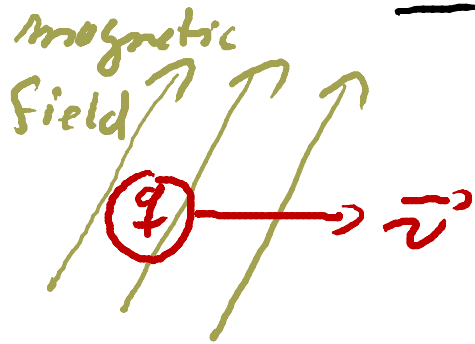
$$\Rightarrow i(t) = -\frac{dq}{dt} = \frac{q_0}{RC} e^{-t/\tau}$$

### • Magnetic Fields $\vec{B}$ :

– are produced by electromagnets (i.e. by moving charges) and by permanent magnets.

No magnetic monopoles (charges)?

$\Rightarrow$  Magnetic Force on a moving charge  $q$ :



$$|F_B| = |q| v_{\perp} B = |q| v B \sin \phi = |q| v B_{\perp}$$

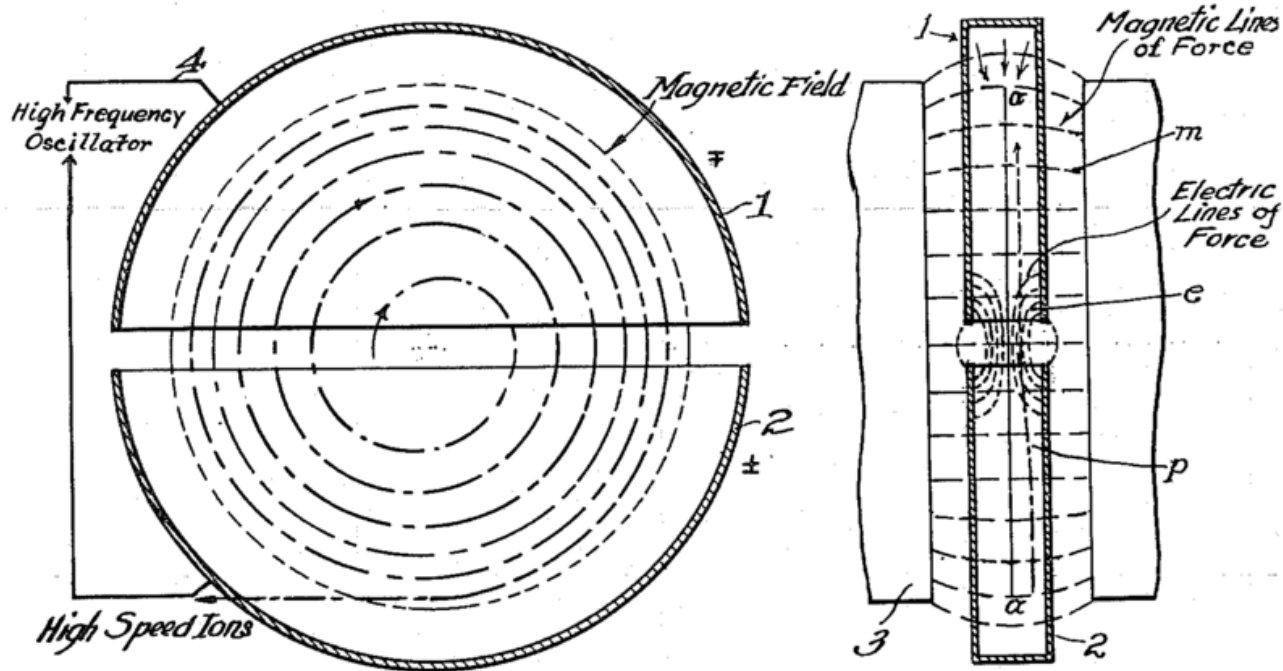
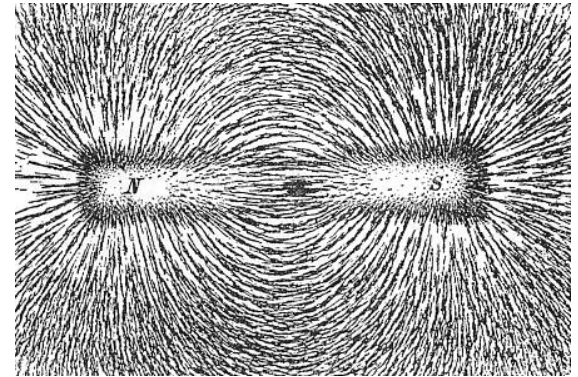
with  $\phi$ : smallest angle between  $\vec{v}$  and  $\vec{B}$  ( $0 \leq \phi \leq 180^\circ$ )

$\Rightarrow$  this equation defines the magnetic field  $B$

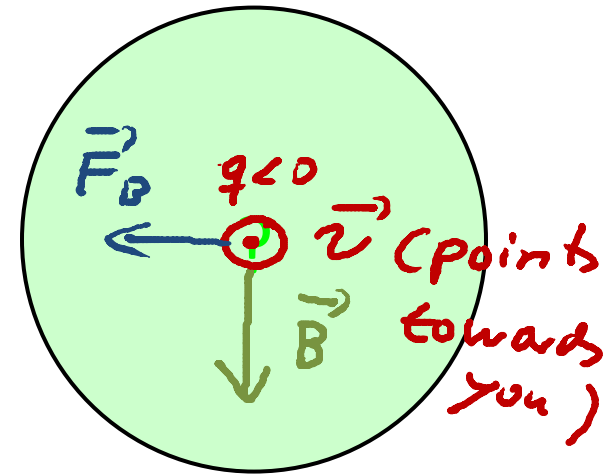
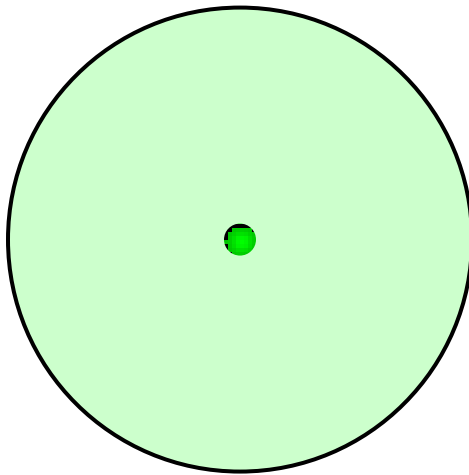
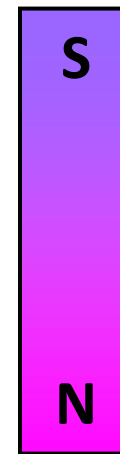
Units:  $[B] = \frac{[F]}{[q][v]} = \frac{N}{C \frac{m}{s}} = \frac{N}{A \cdot m} \equiv \underline{\underline{1 \text{ tesla} = 1 T}}$   
 $= \underline{\underline{10^4 \text{ gauss}}}$

# Today:

- Magnetic field
- Magnetic field lines
- Charge moving in a uniform B-field
  - Particle accelerators: The cyclotron and synchrotron



A beam of electrons traveling directly towards you produces a bright spot when it hits a CRT screen.



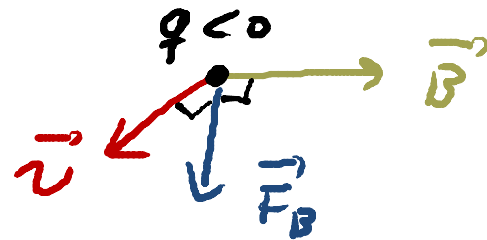
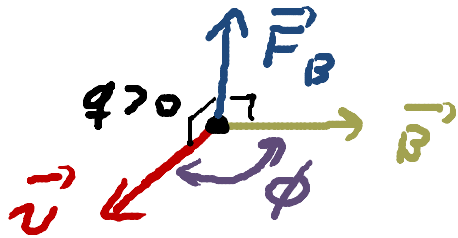
If a magnet with its north pole facing down is brought near the beam from above, which way will the spot on the screen move?

- A.  $\uparrow$     B.  $\downarrow$     C.  $\leftarrow$     D.  $\rightarrow$     E. It won't move.

# Which way does $\vec{F}_B$ point?

- magnitude of force:  $|F_B| = |q| v B \sin \phi$

- Direction:  $\vec{F}_B$  always point perpendicular to the velocity  $\vec{v}$  and magnetic field  $\vec{B}$ , i.e.  $\perp$  to plane defined by  $\vec{v}$  and  $\vec{B}$ , in direction shown below:



- Mathematical shorthand: Cross-product of 2 vectors

$$\vec{F}_B = q \vec{v} \times \vec{B} = q v B \sin \phi \vec{n}$$

↑  
cross product

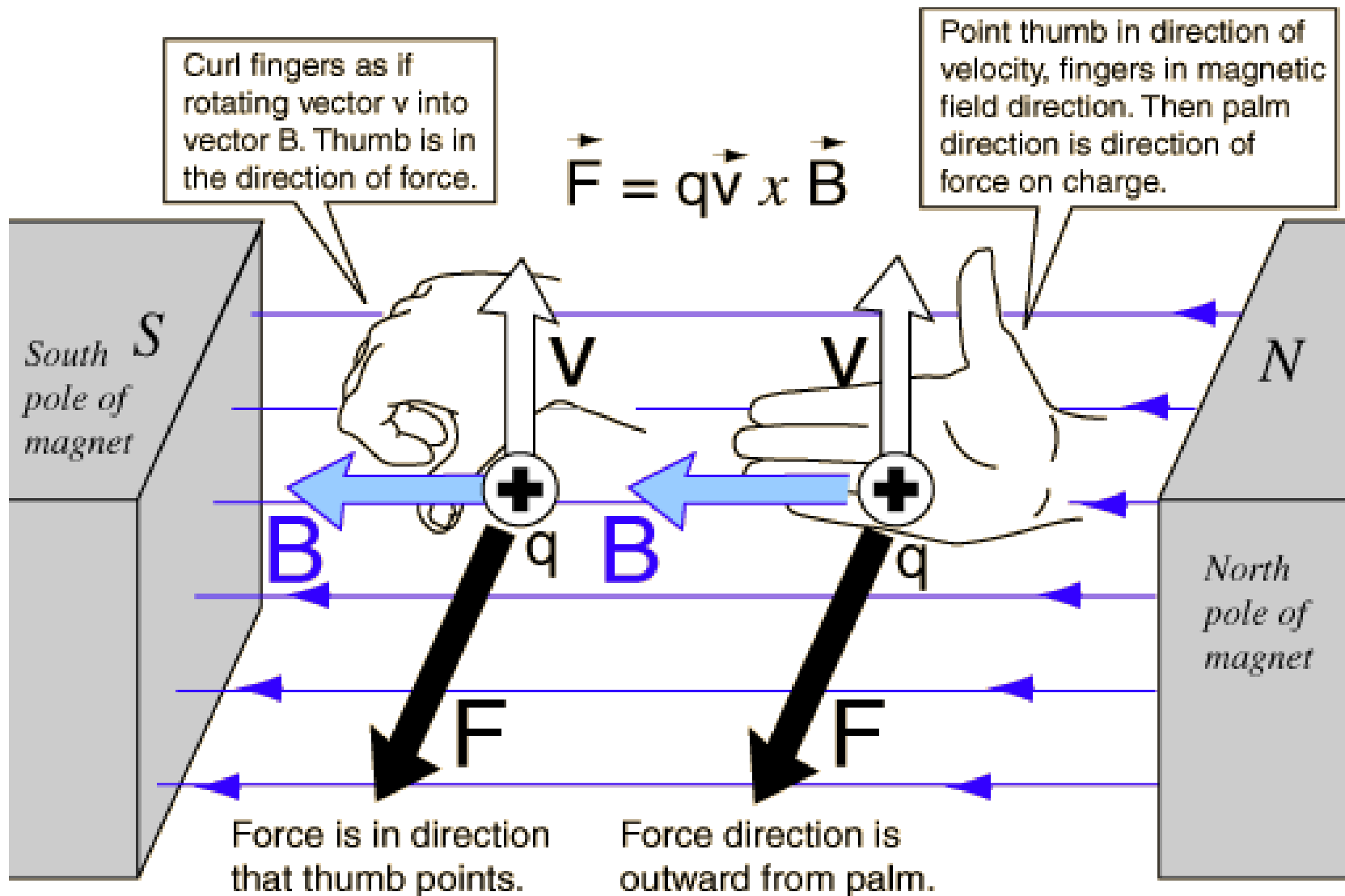
↑  
unit vector  
 $|\vec{n}| = 1$

Use "right hand rule" to find direction

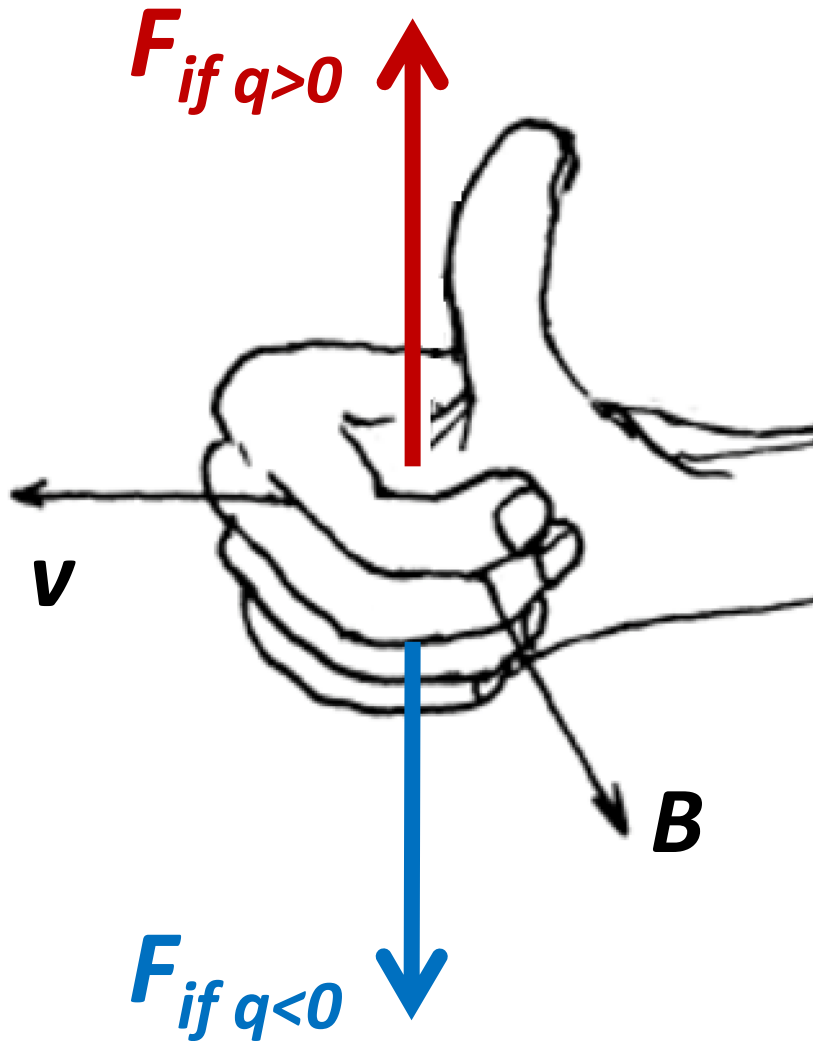
A diagram illustrating the right-hand rule. A red vector labeled "1st vector ( $\vec{v}$ )" points down and to the left. A green vector labeled "2nd vector ( $\vec{B}$ )" points to the right. A blue vector labeled " $\vec{n}$ " points vertically upwards, perpendicular to the plane formed by the two vectors. A right-angle symbol is shown at the intersection of  $\vec{n}$  and the plane.

# “Right Hand Rule”:

Must use your right hand! The figure below shows the force for a positive charge, i.e.  $q > 0$ !!

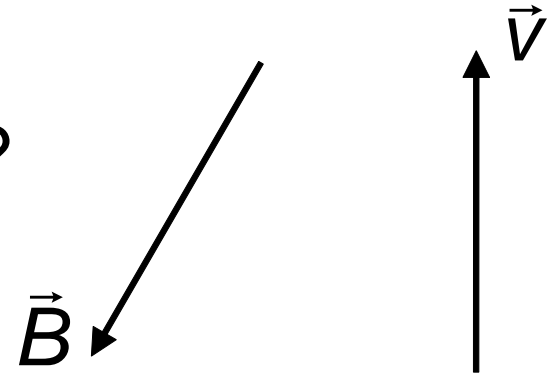


# “Right Hand Rule”: Must use your right hand!!!



- *FINGERS* of the right hand point in the direction of the *FIRST* vector ( $\mathbf{v}$ ) in the cross product,
- then adjust your wrist so that you can bend your fingers (at the knuckles!) toward the direction of the second vector ( $\mathbf{B}$ );
- extend the thumb. If charge is **positive** the force is in direction that the thumb points!
- If charge is **negative**, the force is opposite to direction that the thumb points!

What is the direction of  $\vec{V} \times \vec{B}$ ?



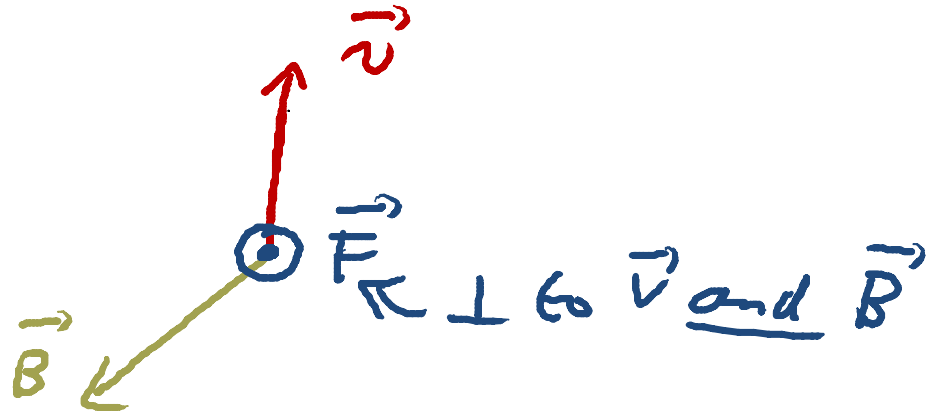
A. ←

B. →

C. ⊙ (out of)

D. ⊗ (into)

E. Other





What is the direction of the magnetic force on the negative charge?

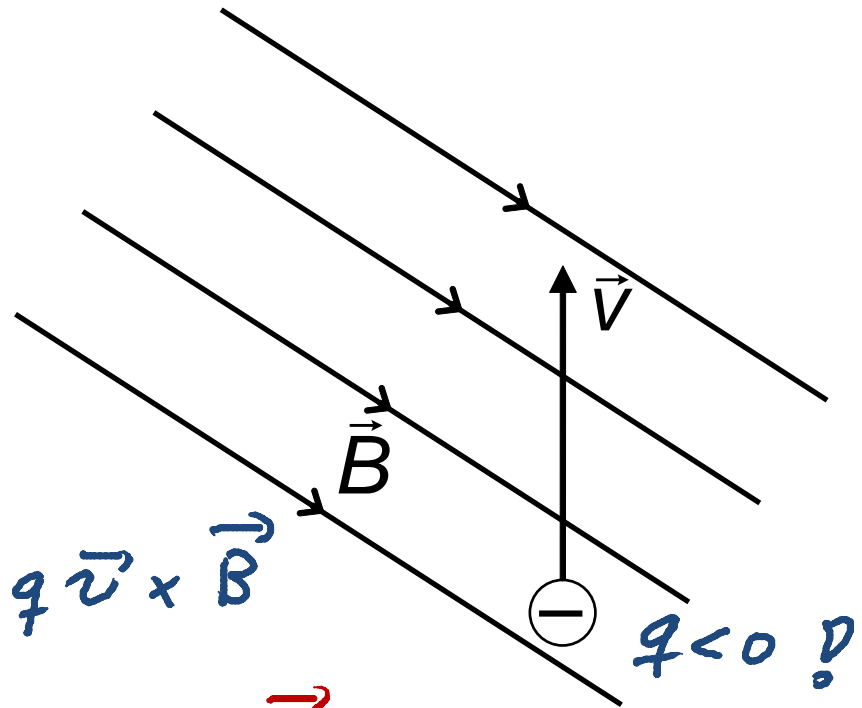
A. ←

B. →

C. ⊙ (out of)

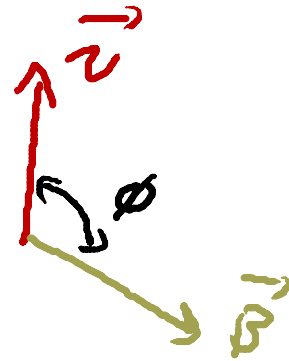
D. ⊗ (into)

E. Other



$$\vec{F} = q \vec{v} \times \vec{B}$$

$q < 0$  !

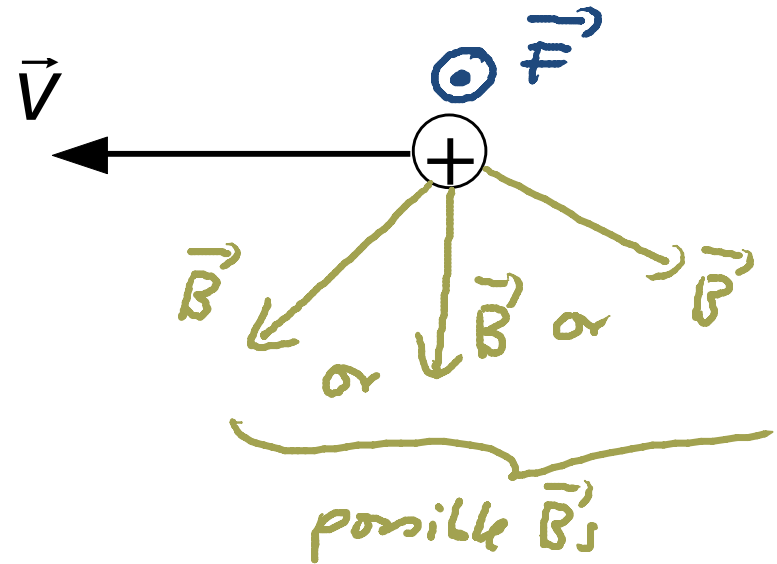


$\vec{v} \times \vec{B}$  points into page!

$\Rightarrow q \vec{v} \times \vec{B}$  points out of page  
 $q < 0$

The magnetic force on the positive charge is directed out of the picture ( $\odot$ ). What is the direction of the magnetic field?

- ~~A.~~  $\leftarrow$
- ~~B.~~  $\rightarrow$
- ~~C.~~  $\odot$  (out of)
- ~~D.~~  $\otimes$  (into)
- E.** Can't tell for sure



# Magnetic Field Line Model

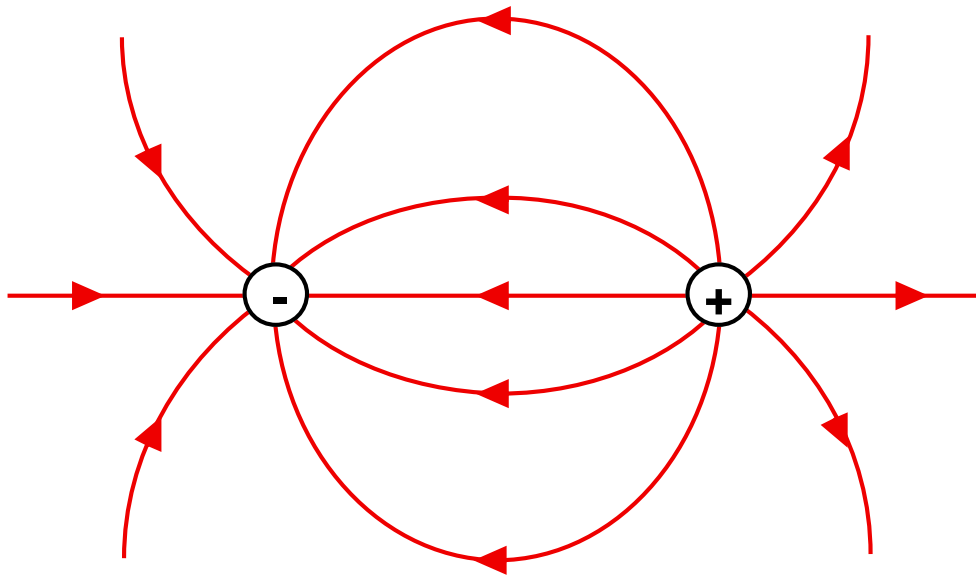
A way of visually representing a magnetic field  
(lines are not real!).

1. Magnetic field lines **point in the direction of the (total) magnetic field** at each point in space.
2. Magnetic field lines **cannot cross**.
3. The **strength (magnitude) of the magnetic field at any place is proportional to the density of field lines** there, i.e.,

$$B \propto \frac{(\# \text{ of field lines})}{(\text{area} \perp \text{ lines})}$$

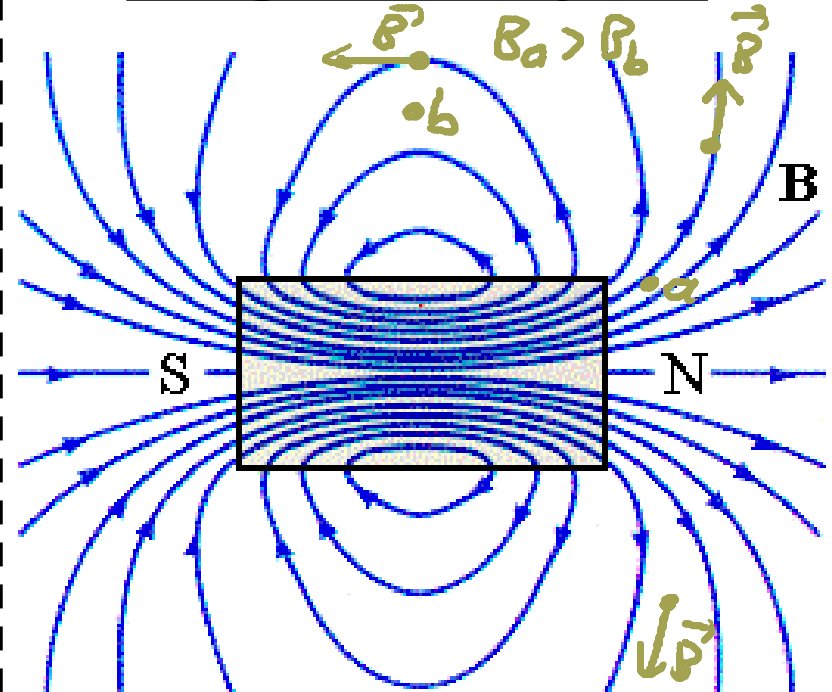
4. **Magnetic field lines never start nor end.** They always form closed loops. This means that there are no isolated magnetic “charges” (monopoles). Magnetic “poles” always occur in N-S pairs.

## Electric Dipole



Electric field lines go from positive to negative electric charge.

## Magnetic Dipole

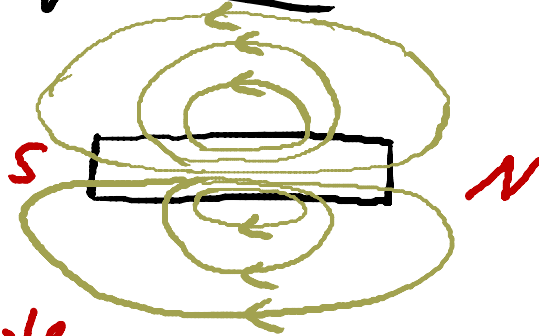


Magnetic field lines never start nor end. They always form closed loops.

# For Permanent Magnets:

→ "field lines" emerge from one end: North pole

→ "field lines" enter other end of magnet: South pole

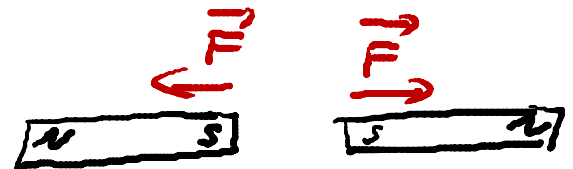
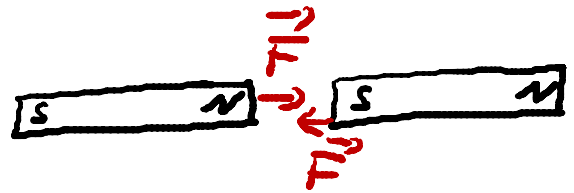


⇒ Magnet has two poles ⇒ magnetic dipole

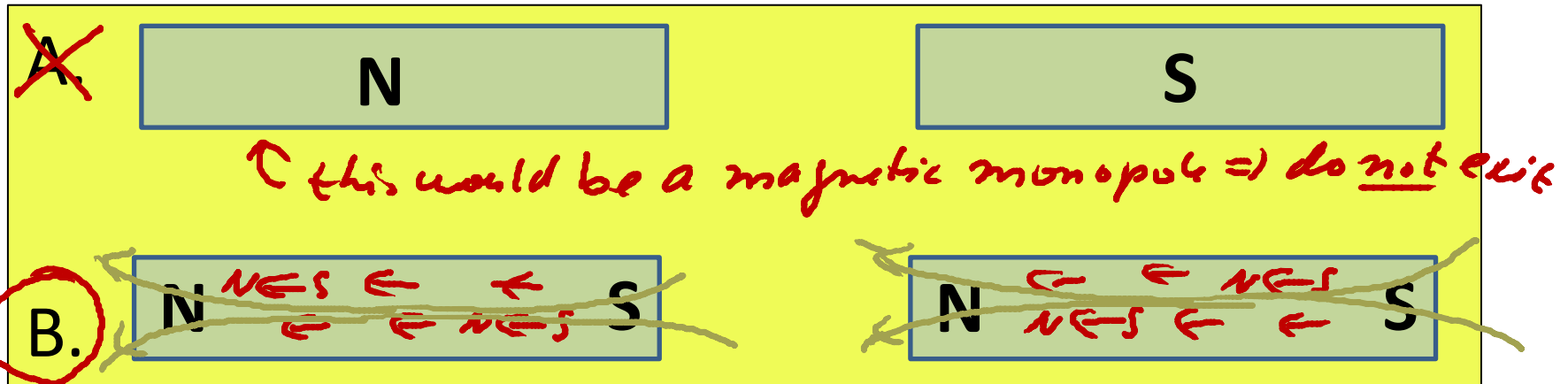
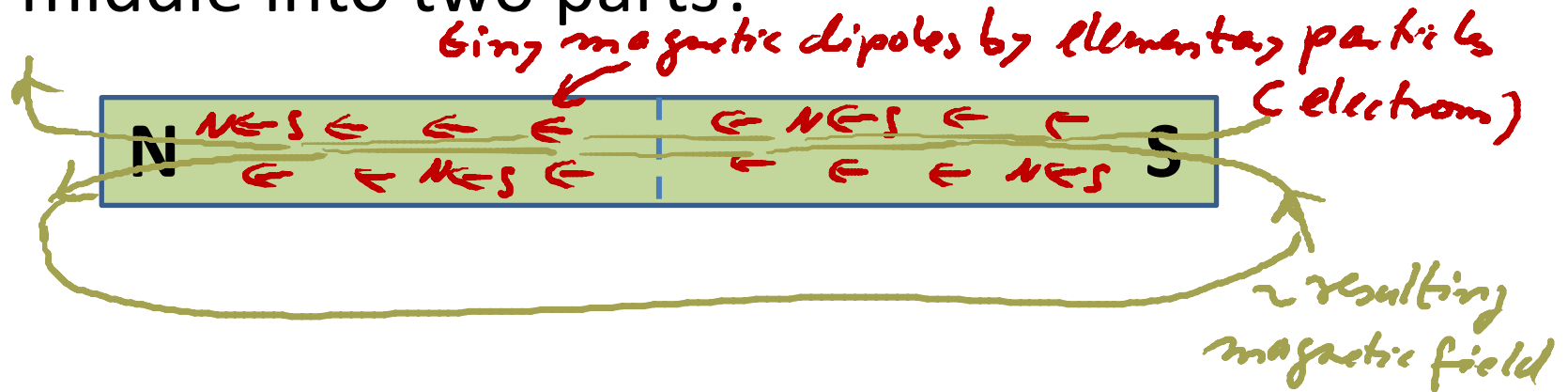
→ for multiple magnets

• Opposite magnetic poles (N and S) attract each other

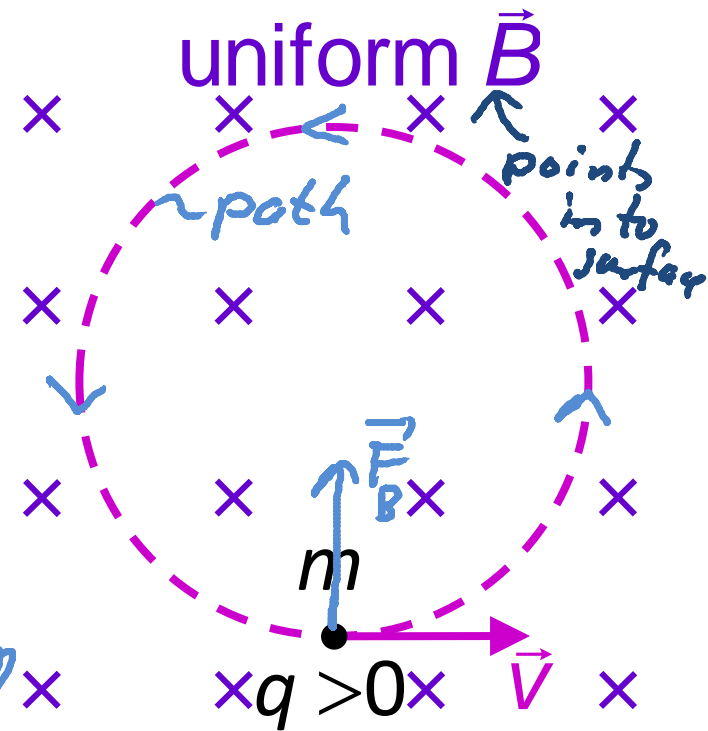
• Like magnetic poles (N and N or S and S) repel each other



What do you get if you cut a bar magnet right in the middle into two parts?



A particle of mass  $m$  and charge  $q > 0$  is moving with speed  $v \perp$  to a **uniform magnetic field**  $B$ .



The particle follows a circular path in the field.  $\vec{F}_B \perp \vec{v}$  always!

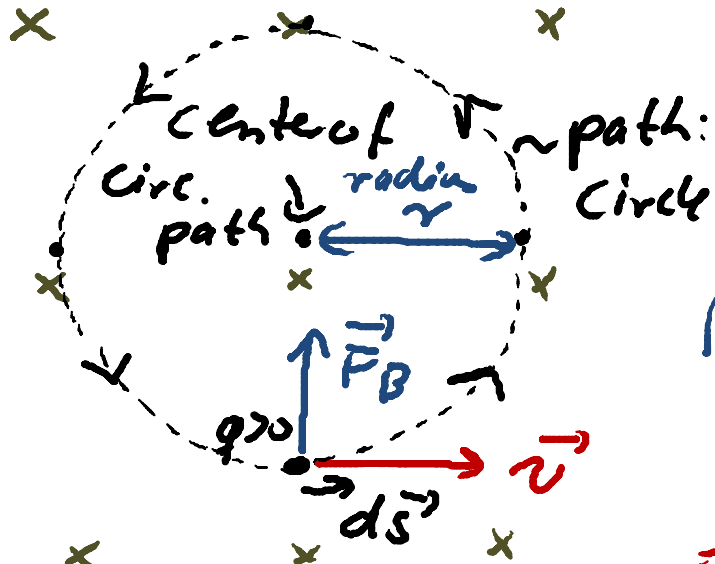
How is the **radius**  $r$  of the particle's path related to its speed  $v$ ?

$$\sum F_{\text{on } q} = F_B = ma = \frac{qvB}{\cancel{v}} = m \frac{v^2}{r} \Rightarrow r = \frac{mv}{qB} \propto v$$

$\uparrow a = v^2/r$  for circ. motion

- A.  $r \propto v$     
  B.  $r \propto v^2$     
 C.  $r \propto v^{-1}$     
 D.  $r \propto v^{1/2}$   
 E.  $r$  does not depend on  $v$

# Circulating Charged Particles



$\vec{F}_B$  is  $\perp$  to  $\vec{v}$  and  $\vec{B}$  always

$\Rightarrow$  charge is moving on circular path here

$$|F_B| = m|a| \Rightarrow |q|vB = m \frac{v^2}{r}$$

$$a = \frac{v^2}{r} \text{ for circ. motion}$$

$\Rightarrow$  radius of circular path:

$$r = \frac{mv}{|q|B} = \frac{\text{momentum } p}{|q|B}$$

Uniform  $\vec{B}$ -field;  
 $\vec{B}$  points into surface

Note:  $\vec{F}_B \perp \vec{v}$  always!  $\Rightarrow \vec{F}_B \perp$  to path always!

$$\begin{aligned} dW &= \vec{F}_B \cdot d\vec{s} \\ &= F_B ds \cos 90^\circ \\ &= \underline{\underline{0}} \end{aligned}$$

$\Rightarrow$  Magnetic force  $\vec{F}_B$  never does any work on moving charge!

$\Rightarrow$  here:  
 $\Delta K = 0$

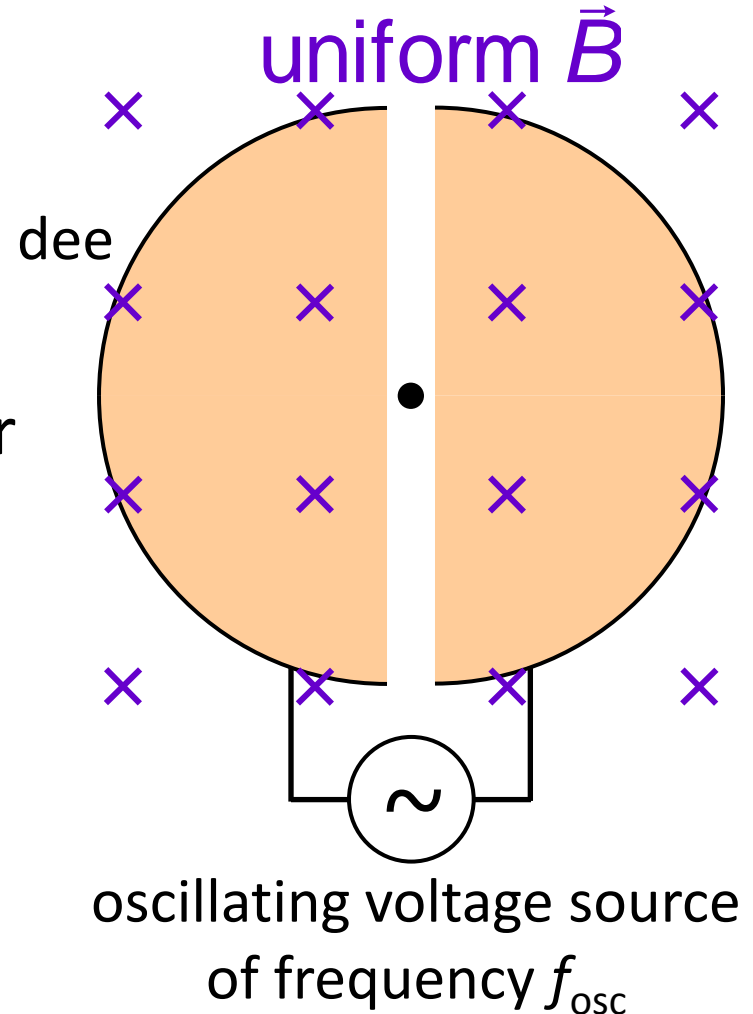
$\Rightarrow |v| = \text{const}$



# Application: Particle Accelerators

## The cyclotron:

- **Fixed magnetic field; changing orbit radius**
- composed of two hollow copper dees that are immersed in a uniform magnetic field & connected to an oscillating voltage source.
- Particles (e.g., protons), each of charge  $q$  & mass  $m$ , start at a source near the center of the dees.



# The Cornell Cyclotron



**The Cornell cyclotron** (2 MeV protons) was built about 1935 and decommissioned in 1956.

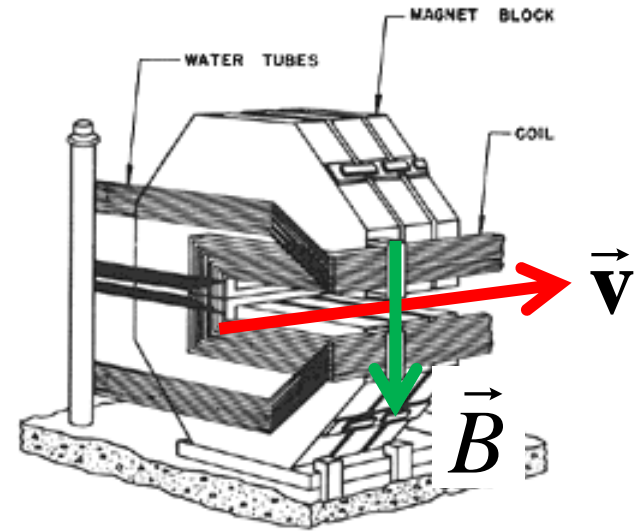
This photo with Assistant Professor Boyce D. McDaniel was taken in 1955.

# Application: Particle Accelerators

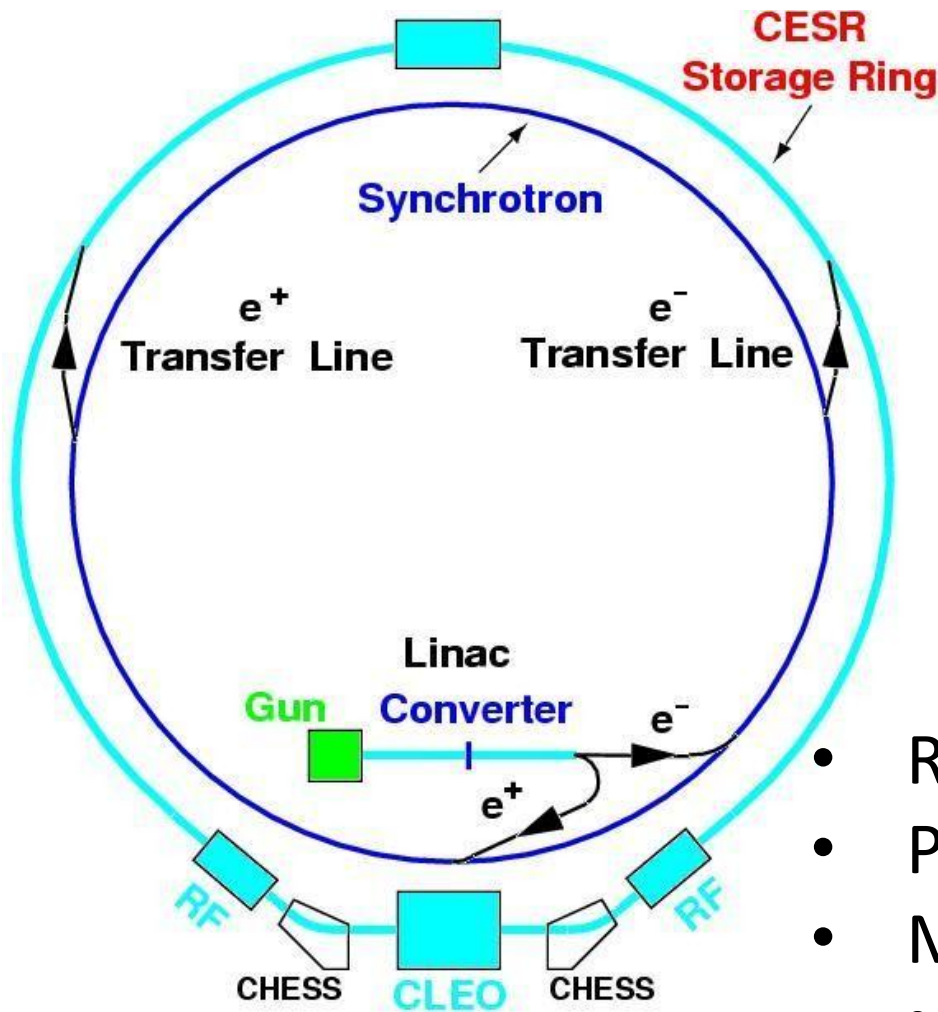
## The synchrotron:

- **Fixed orbit radius; magnetic field adjusted for particle momentum/energy**
- “Dipole magnets” keep particles on fixed orbit.

$$Radius = \frac{p(t)}{qB(t)} = \text{const.}$$



# The Cornell Synchrotron



- Radius = 122 m
- Particle energy: up to 5 GeV
- Magnetic bending fields: up to  $\sim 0.2$  T ( $\sim 3000*$  Earth's magnetic field)